

Data sheet for three-phase Squirrel-Cage-Motors Innomotics



Motor type : 1AV3104A INNOMOTICS GP - 100 L - IM B3 - 2p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data														Safe Area			
U [V]	Δ / Y	f [Hz]	P [kW]	P [hp]	I [A]	n [1/min]	M [Nm]	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N T _I /T _N	M _K /M _N T _B /T _N	IE-CL
DOL duty (S1) - 155(F) to 130(B)																	
400	Δ	50	3.00	-/-	5.70	2910	9.8	87.1	87.7	87.0	0.87	0.82	0.72	9.4	4.4	4.5	IE3
690	Y	50	3.00	-/-	3.30	2910	9.8	87.1	87.7	87.0	0.87	0.82	0.72	9.4	4.4	4.5	IE3
460	Δ	60	3.45	-/-	5.60	3505	9.4	88.5	88.5	87.5	0.87	0.83	0.73	10.0	4.0	4.8	IE3
460	Δ	60	3.00	-/-	5.00	3525	8.1	88.5	88.2	86.7	0.85	0.80	0.69	11.2	4.6	5.6	IE3
IM B3 / IM 1001		FS 100 L		IP55		UKCA		IEC/EN 60034			IEC, DIN, ISO, VDE, EN						
Environmental conditions : -20 °C - +40 °C / 1000 m									Locked rotor time (hot / cold) : 9.00 s 12.10 s								

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	72.0 / 80.0 dB(A) _{2) 3)}	75.0 / 83.0 dB(A) _{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0041 kg m²		Thermal class	F
Bearing DE NDE	6206 2Z C3	6206 2Z C3	Duty type	S1
Bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	aluminum
Regreasing device	Without		Net weight of the motor (IM B3)	25 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Preloaded bearing DE		Color, paint shade	RAL7030
Condensate drainage holes	Without		Motor protection	(B) 3 PTC thermistors - for tripping (2 terminals)
External earthing terminal	Without		Method of cooling	IC411 - self ventilated, surface cooled
			Carbon footprint (without options)	125kg

Terminal box

Terminal box position	top	Main cable entry	2xM32x1.5
Material of terminal box	Aluminium	Main cable gland	2 plugs
Type of terminal box	TB1 F00	Auxiliary cable entry	1xM16x1.5
Contact screw thread	6xM4	Auxiliary cable gland	1 plug
Max. cross-sectional area	4.0 mm²		

I_A/I_N = locked rotor current / current nominal
M_r/M_N = locked rotor torque / torque nominal
M_K/M_N = break down torque / nominal torque
1) L_{10mh} according to DIN ISO 281 10/2010
2) at rated power / at full load
3) Value is valid only for DOL operation with motor design IC411

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INNOMOTICS	Document type Technical data sheet			Document status Released			
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Restricted © Innomotics 2026				Revision AA	Creation date 2026-05-12	Language en	Page 1/2

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Special design

H01 Bolted on mounting feet (instead of cast)

I_{Δ}/I_N = locked rotor current / current nominal
 M_{Δ}/M_N = locked rotor torque / torque nominal
 M_b/M_N = break down torque / nominal torque

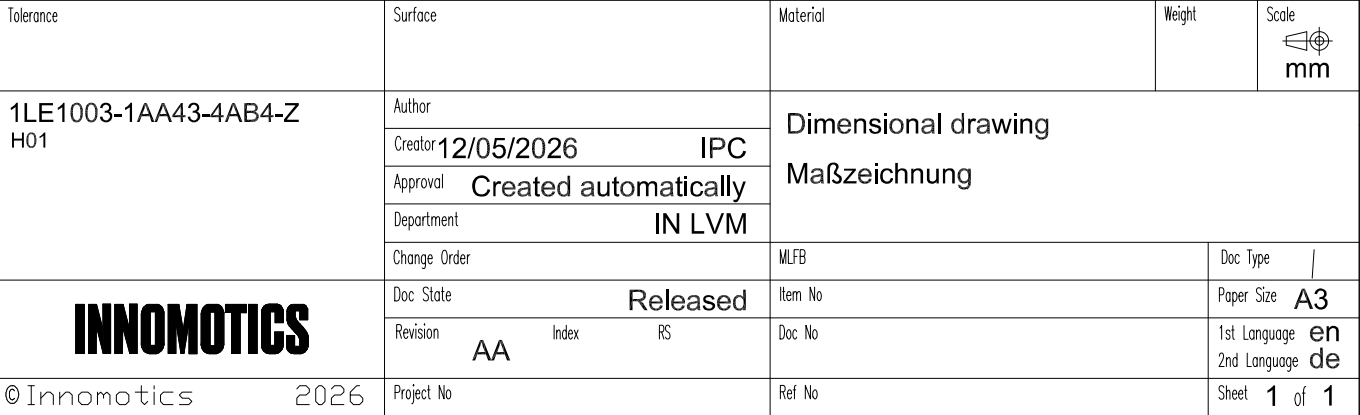
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